

CS 331, Fall 2026

Today: Data structures

Mini-lecture 3 (9/2)

Data structures

Many algos require same subroutines.

- Maintain a set of items
- Find smallest item
- Predecessor / successor / search / ...

Data structure = be **lazy** & solve just once

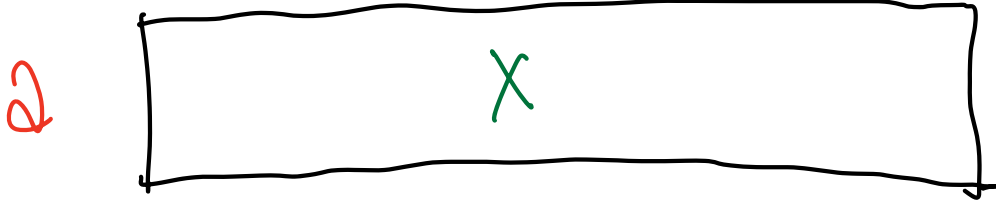
Reusable abstraction of common subroutines

Presented as an API: inner workings irrelevant
today

Notation

$x, y, z \leftarrow$ objects,
fit in $O(\log(n))$ -bit words

$a, b, c \leftarrow$ addresses where objects stored



address
 $a = \& x$
 $x = *a$
dereference

Lists (Part I, Section 7.1)

Goal: maintain set of objects w/ indices

Supported operations:

- Insert
- Delete
- Query

} ideally, $O(1)$ time?

Array

↪ size

Cost

API: $\text{init}(n)$

$O(1)$

$\text{Insert}(x, i)$

$O(1)$

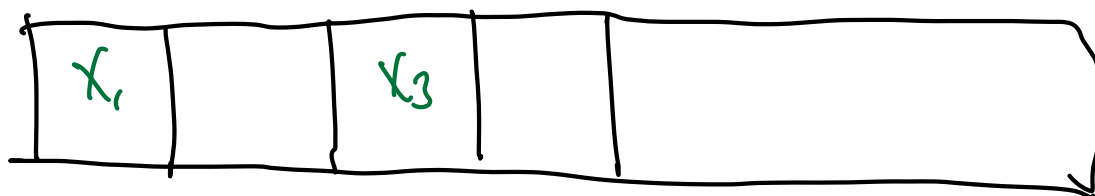
$\text{Delete}(i)$

$O(1)$

$\text{Query}(i)$

$O(1)$

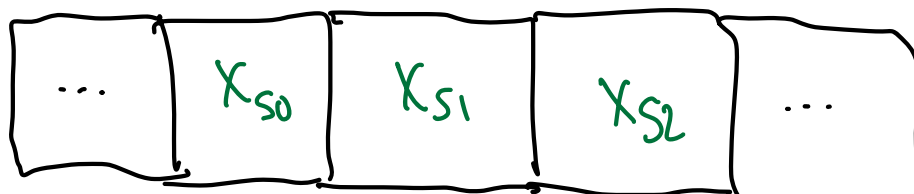
$2, 2+w, 2+2w, \dots$



$w = \text{word length}$

index $i \equiv$

What's it bad at?

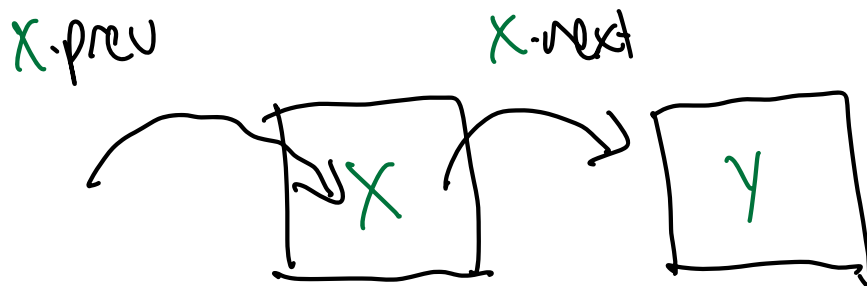


x ↪

Linked List

Key idea: if you know $\textcolor{red}{a} = \&\textcolor{green}{x}$

Can easily manipulate $\textcolor{green}{x}$'s neighbors



Tradeoff: dynamic indices

API: $\text{init}()$ $O(1)$

$\text{insertAfter}(\textcolor{green}{x}, \textcolor{red}{a})$ $O(1)$

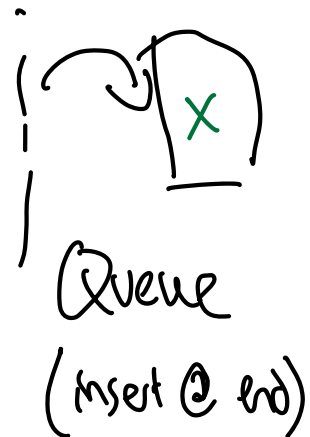
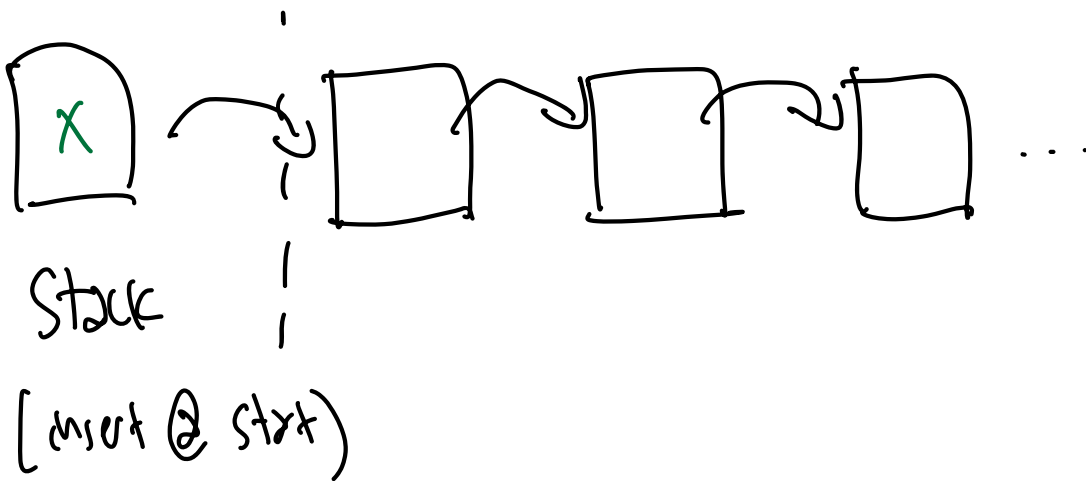
$\text{delete}(\textcolor{red}{a})$ $O(1)$

$\text{query}(\textcolor{red}{a})$ $O(1)$

Q: how long would these take if $\textcolor{red}{a} = \text{index}$?

Stack/Queue

Restricted LinkedList (can simplify algo code!)



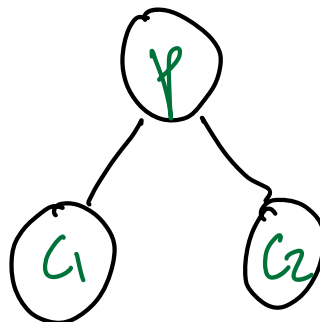
Stack: Push(x), Pop(),

Queue: Queue(x), Dequeue(),

Peek() = all $O(1)$

Heaps (Part I, Section 7.2)

Heap invariant:
"smaller rises"

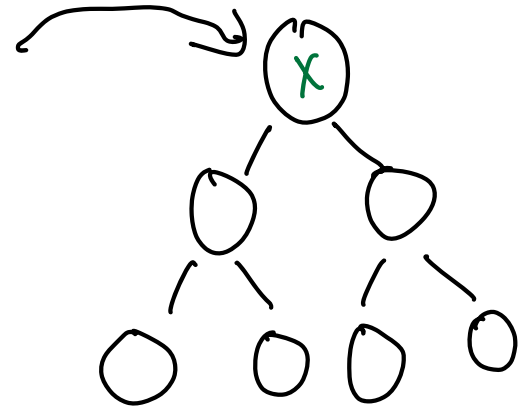


$$p \leq c_1$$

$$p \leq c_2$$

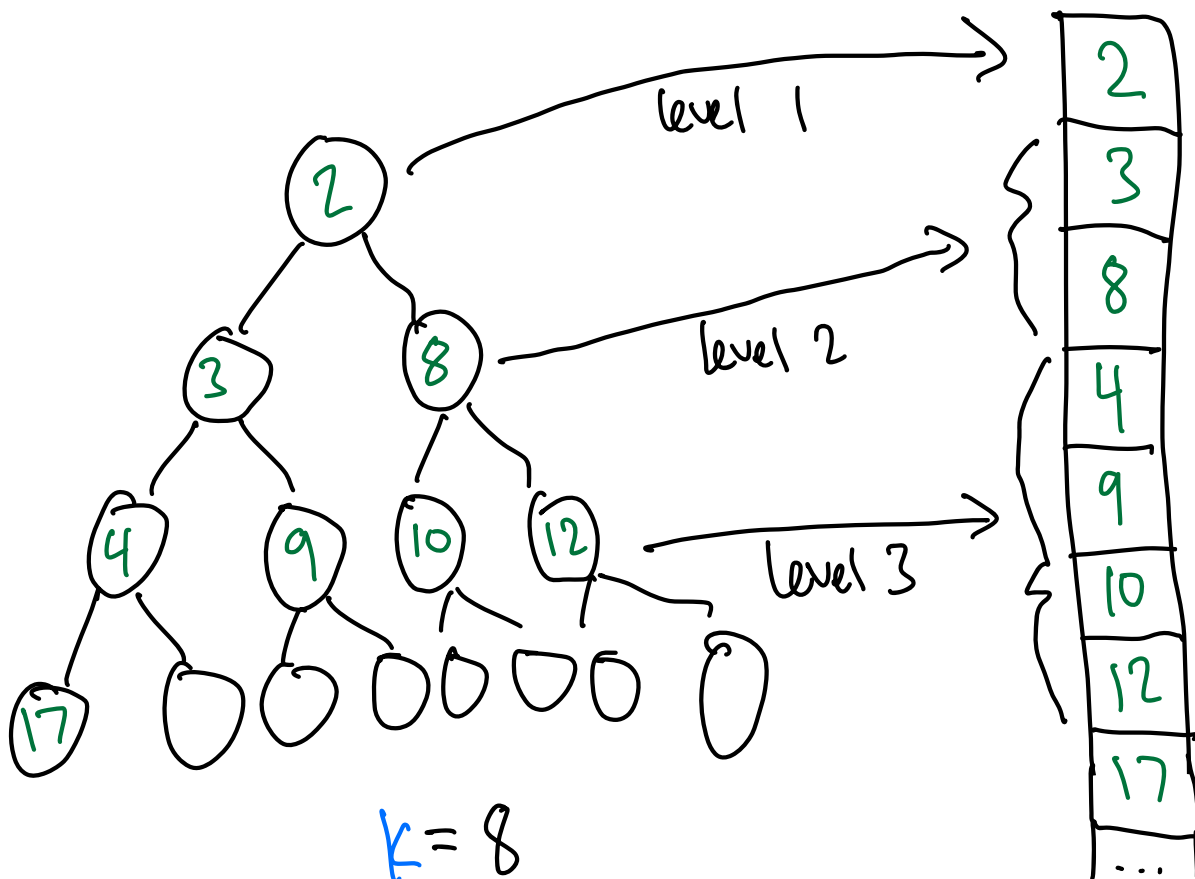
Heaps always maintain heap invariant after steps!

PeekMin() = $O(1)$ time

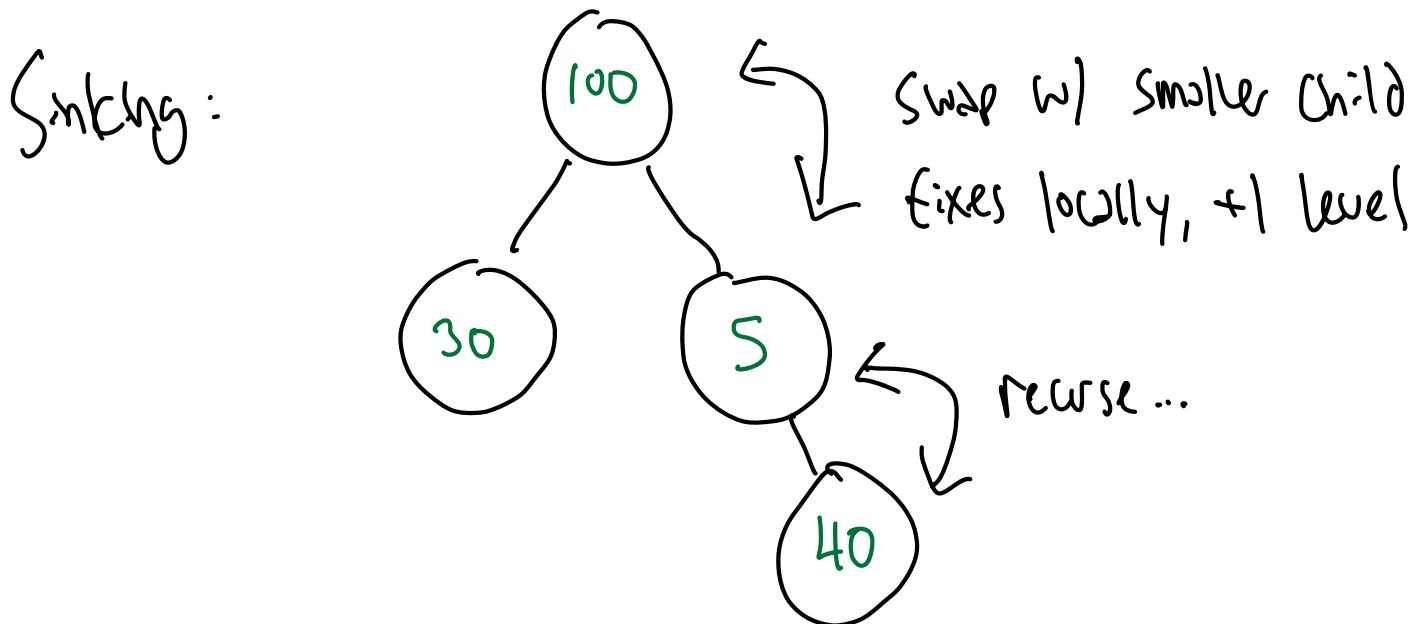


ExtractMin() = $O(\log(n))$ time
max #
objects

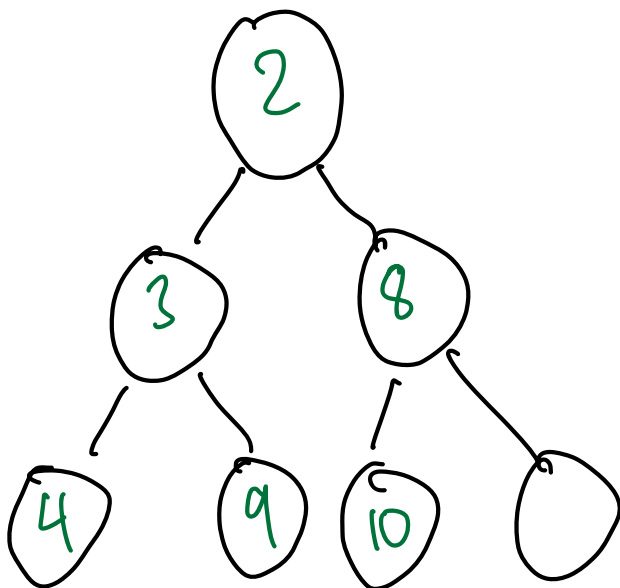
Idea: always maintain as 1st k entries in
binary tree $\equiv$ Array in background



- To Extract Min(),
- Swap 1st & k^{th} objects
 - delete k^{th} object, $k--$
- $O(\log(n))$ time $\rightarrow$
- let 1st object "sink"



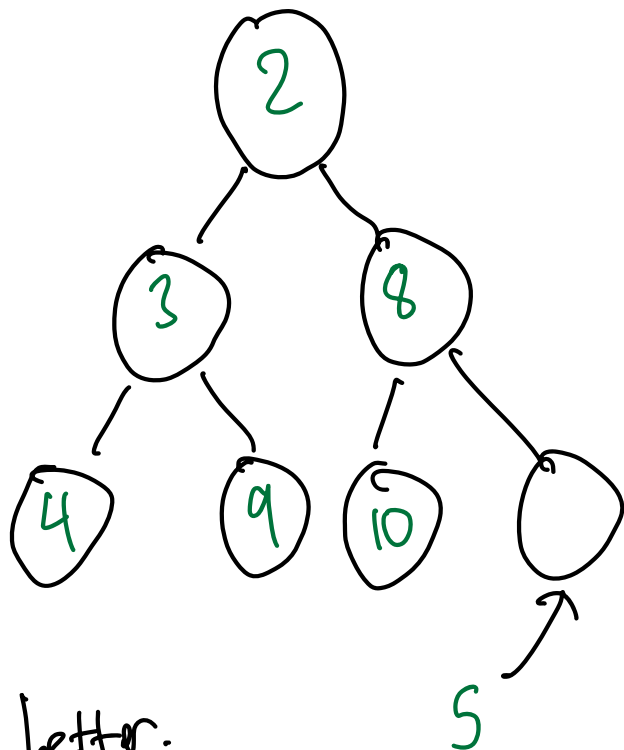
Delete(a): $O(\log(n))$ time if you know where it is



- Swap with k^{th}
- delete k^{th} , $k--$
- let old k^{th} sink

Insert(x): $O(\log n)$ time

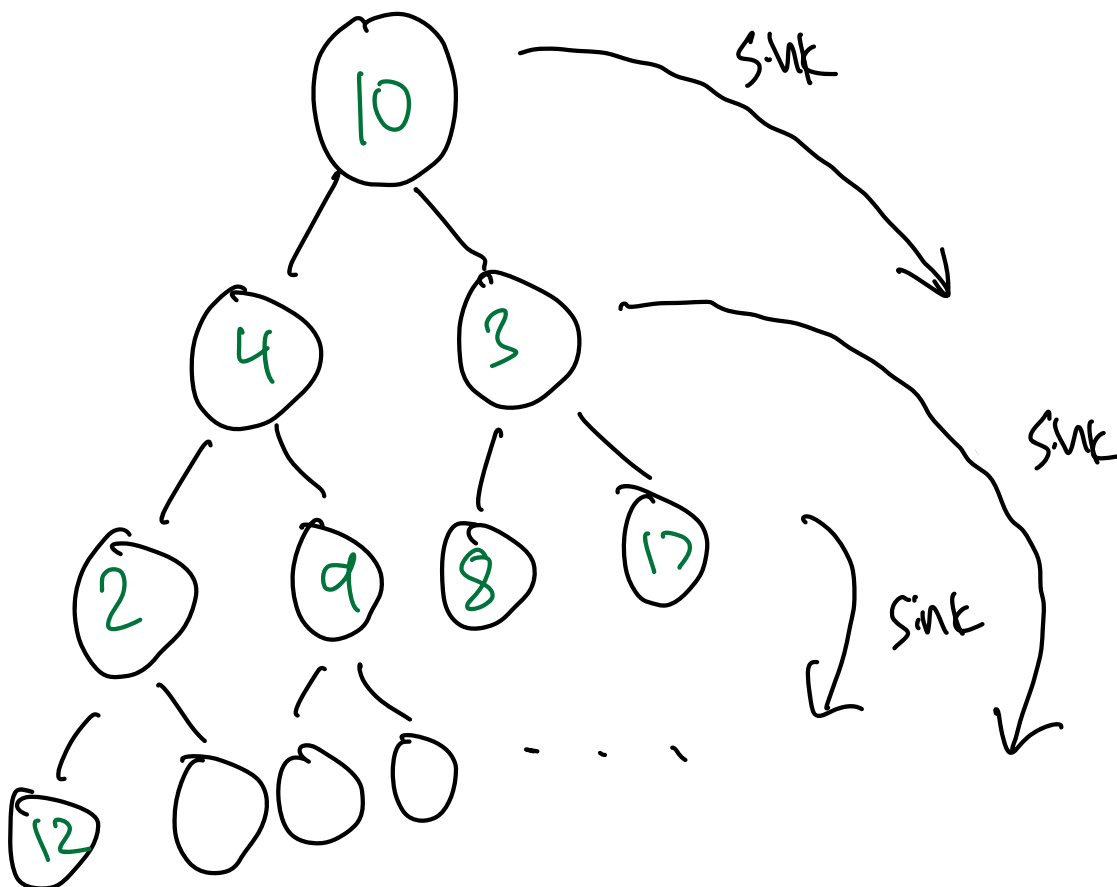
- add at end, $k++$
- let new object "float"
(swap w/ parent if smaller)



Old objects can't create

issues: heap invariant only gets better.

Init(): $O(n)$ time



$1 \times h$

$2 \times (h-1)$

$4 \times (h-2)$

$\vdots$
 $n/2 \times 1$

bottom heavy

Binary Search Trees (Part I, Section 7.3)

Motivation: Linked List insert = $O(1)$

search = $O(n)$

Can we balance costs?

"Sorted List"

insert = $O(\log n)$

search = $O(\log(n))$

Yes! This is what BST does. (+ more)

API: Search (x)

Insert (x)

Delete (x)

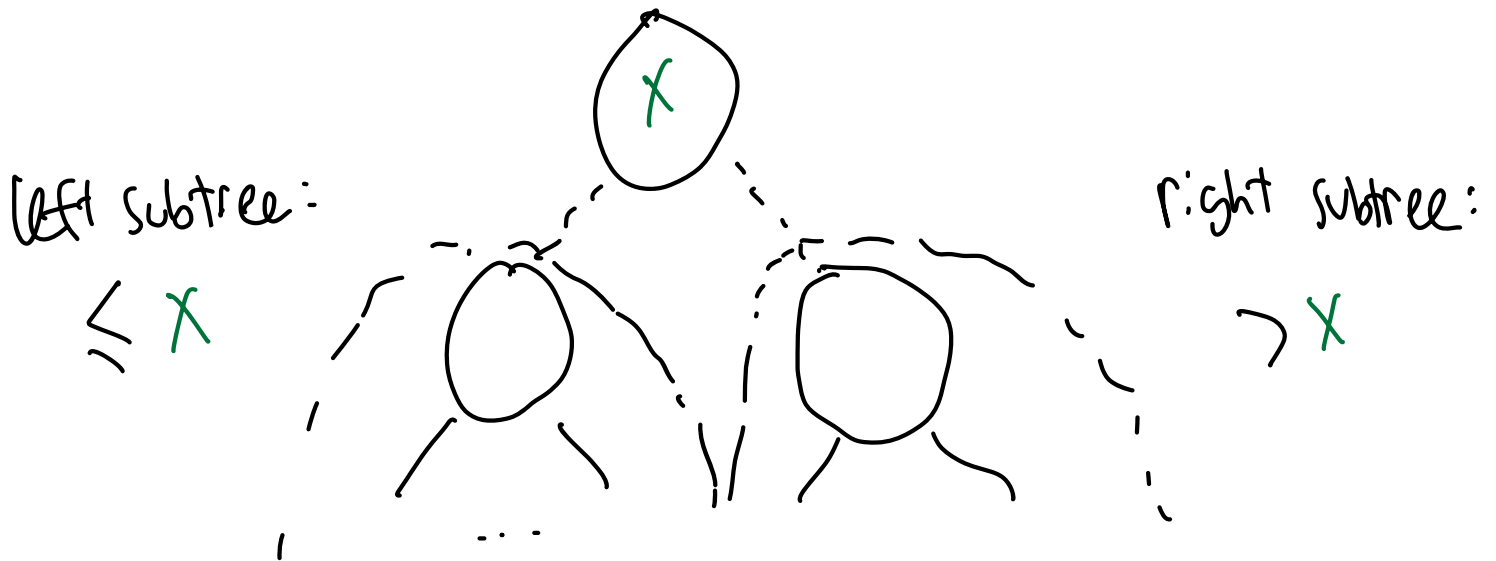
Query (i)

Index (x)

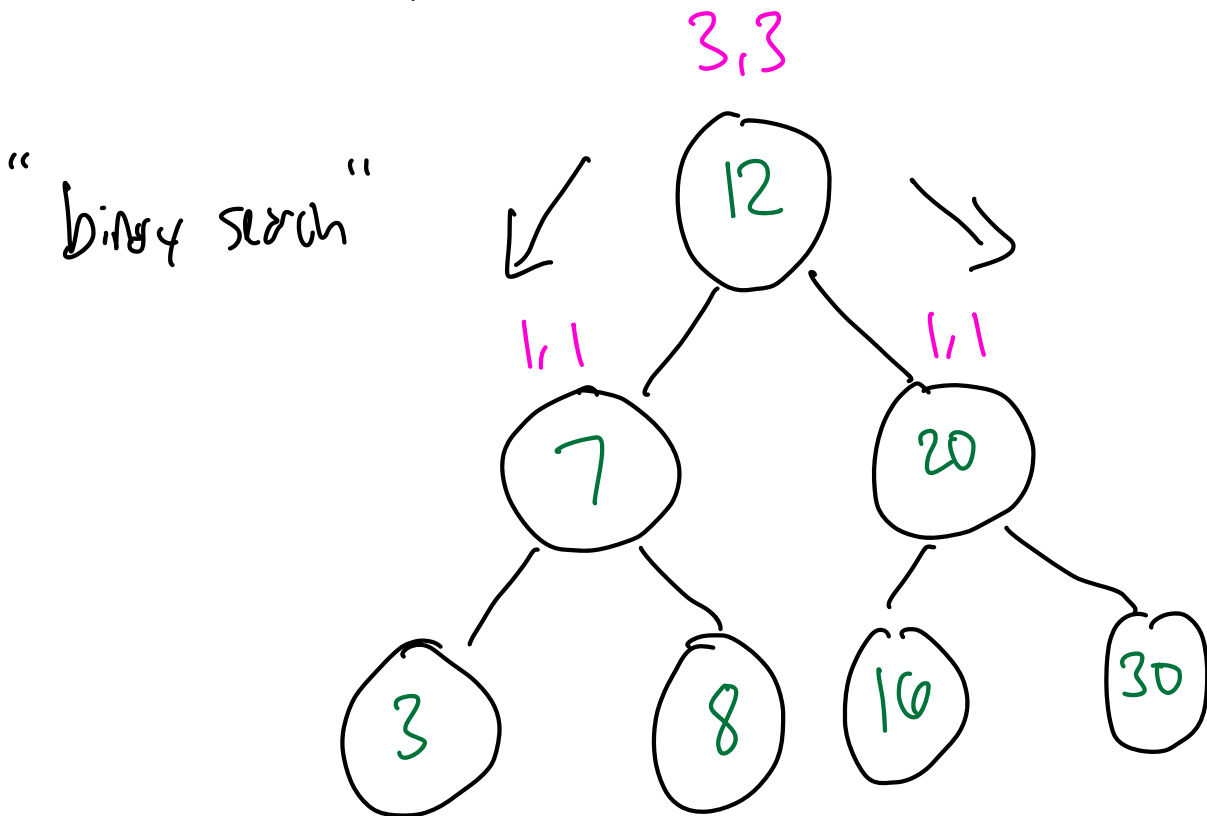
} all $O(\log(n))$

Ex: implement predecessor

BST invariant



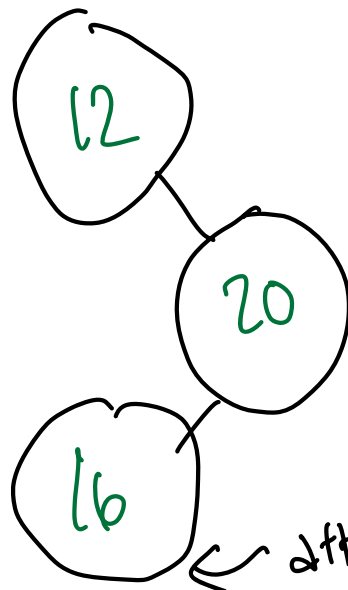
Search(x) = height of tree h



Index / Query: augment w/ subtree sizes

Simple Insert: Search + attach

$x = 19$

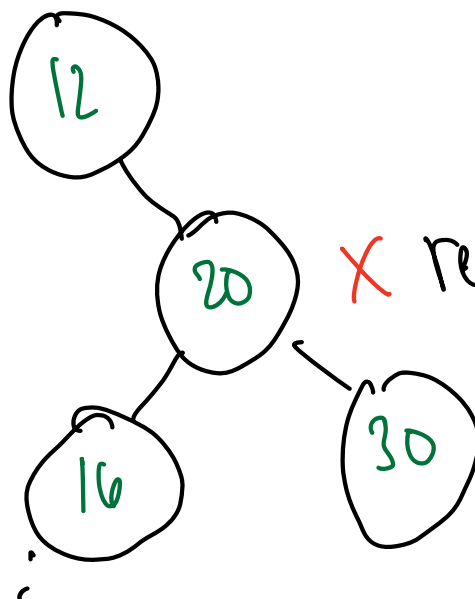


all subtrees
correct

← attach here

Simple Delete: Search + splice

$x = 20$



X replace w/
predecessor
= left node

only hard case:
two children

Hard part: maintaining $h = O(\log(n))$
AVL tree, red black tree